



On Fundamental Solutions and Gaussian Bounds for Degenerate Parabolic Equations with Time-dependent Coefficients

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Abstract

We consider second order degenerate parabolic equations with real, measurable, and time-dependent coefficients. We allow for degenerate ellipticity dictated by a spatial A_2 -weight. We prove the existence of a fundamental solution and derive Gaussian bounds. Our construction is based on the original work of Kato (Nagoya Math. J. **19**, 93–125 1961).

Keywords Gaussian bounds · Degenerate parabolic equations · Kato problem · Heat kernel

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1 Introduction

We consider parabolic operators of the form

$$\mathcal{H}u := \partial_t u + \mathcal{L}u := \partial_t u - w^{-1} \operatorname{div}_x (A(x, t) \nabla_x u), \quad (x, t) \in \mathbb{R}^n \times \mathbb{R} =: \mathbb{R}^{n+1}, \quad (1.1)$$

where the weight $w = w(x)$ is time-independent and belongs to the spatial Muckenhoupt class $A_2(\mathbb{R}^n, dx)$, and the coefficient matrix $A = A(x, t)$ is measurable with real entries and possibly depends on all variables. Degeneracy of A is also dictated by the weight w in the sense that A satisfies

$$c_1 |\xi|^2 w(x) \leq A(x, t) \xi \cdot \xi, \quad |A(x, t) \xi \cdot \zeta| \leq c_2 w(x) |\xi| |\zeta|, \quad (1.2)$$

for some $c_1, c_2 \in (0, \infty)$ and for all $\xi, \zeta \in \mathbb{R}^n$, $(x, t) \in \mathbb{R}^{n+1}$. We refer to $[w]_{A_2}$ as the constant of the weight and to c_1, c_2 as the ellipticity constants of A . We will frequently refer to n, c_1, c_2 , and $[w]_{A_2}$ as the structural constants.

Equations and operators as in Eq. 1.1 appear naturally in the study of the fractional powers of parabolic equations and anomalous diffusions, see [17] and the references therein, and in the context of heat kernels of Schrödinger equations with singular potential, see

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[14]. For contributions to the study of local properties of the solutions to $\mathcal{H}u = 0$ and the Gaussian estimates, we refer to [5, 8]. Furthermore, recently in [4] we, together with M. Egert, established the Kato (square root) estimate for \mathcal{H} allowing also for complex coefficients. While this may be considered as of independent interest, the result proved here and the results of [3] will be combined in a forthcoming work to give a generalization of the work in [4] to weighted parabolic operators as in Eq. 1.1 satisfying Eq. 1.2.

Given $0 < T < \infty$, we in this paper consider the Cauchy problem

$$\begin{aligned} \text{(i)} \quad & \mathcal{H}u = \partial_t u - w^{-1} \operatorname{div}_x(A(x, t)\nabla_x u) = 0 \text{ in } \mathbb{R}^n \times (0, T), \\ \text{(ii)} \quad & \lim_{t \rightarrow 0} u(x, t) = f(x). \end{aligned} \tag{1.3}$$

The equation in (i) is interpreted in the weak sense and according to the following definition. We refer to the bulk of the paper for definitions and the functional setting.

Definition 1.1 A weak solution to Eq. 1.3 (i) on $\mathbb{R}^n \times (0, T)$ is a (real-valued) function $u \in L^2_{\text{loc}}((0, T], H^1_{w, \text{loc}}(\mathbb{R}^n))$ such that

$$\int_0^T \int_{\mathbb{R}^n} u(x, t) \partial_t \phi(x, t) \, dw \, dt = \int_0^T \int_{\mathbb{R}^n} A(x, t) \nabla_x u(x, t) \cdot \nabla_x \phi(x, t) \, dx \, dt \tag{1.4}$$

for all $\phi \in C_0^\infty(\mathbb{R}^n \times (0, T))$.

The purpose of this note is to establish the existence of a kernel/fundamental solution associated to \mathcal{H} , to derive appropriate Gaussian upper bounds for the kernel in the nature of the original (unweighted) estimates of Aronson [1], and to use the kernel to represent weak solutions to Eq. 1.3. The quantitative estimates derive will only depend on n, c_1, c_2 , and $[w]_{A_2}$, i.e., on the structural constants.

Recall that in the case of uniform elliptic coefficients, i.e., $w \equiv 1$, the problem in Eq. 1.3 was studied in depth in [2]. In [2] Aronson considered the energy space $L^\infty([0, T], L^2(\mathbb{R}^n)) \cap L^2((0, T], H^1(\mathbb{R}^n))$, he proved that all solutions u in this space have a trace $f \in L^2(\mathbb{R}^n)$, and the solution is uniquely determined by this trace. He obtained existence, given initial data in L^2 , and hence he defined an evolution operator Γ such that $u(\cdot, t) = \Gamma(\cdot, t)f$ for $t > 0$. In [1], pointwise Gaussian estimates of the evolution operator are proved. This result allows one to define weak solutions to Eq. 1.3 by the integral representation

$$u(x, t) = \int_{\mathbb{R}^n} K_t(x, y) f(y) \, dy = \int_{\mathbb{R}^n} K(x, t, y, 0) f(y) \, dy, \tag{1.5}$$

for f in various spaces of initial conditions, where K is the kernel/fundamental solution associated to \mathcal{H} . Uniqueness is proved in the class of the solutions satisfying

$$\int_0^T \int_{\mathbb{R}^n} e^{-a|x|^2} |u(x, t)|^2 \, dx \, dt < \infty, \tag{1.6}$$

for some $a > 0$, and existence whenever $f \in L^2(e^{-\gamma|x|^2} dx)$. In particular, this result covers the case $f \in L^p(dx), 2 \leq p \leq \infty$.

Given $x \in \mathbb{R}^n, t > 0$, we introduce $w_t(x) =: w(B_{\sqrt{t}}(x))$ where $B_{\sqrt{t}}(x)$ is the Euclidean ball of radius \sqrt{t} and center x in \mathbb{R}^n . This note is devoted to the proof of the following result.

Theorem 1.2 Given $f \in L^2_w(\mathbb{R}^n)$ and $T > 0$, there exists a unique weak solution to the problem in Eq. 1.3, such that

$$u \in L^\infty([0, T], L^2_w(\mathbb{R}^n)) \cap L^2((0, T], H^1_w(\mathbb{R}^n)), \tag{1.7}$$

and

$$u(\cdot, t) \rightarrow f(\cdot) \text{ in } L^2_w(\mathbb{R}^n) \text{ as } t \rightarrow 0^+. \tag{1.8}$$

The unique solution u can be represented as

$$u(x, t) = \int_{\mathbb{R}^n} K_t(x, y) f(y) w(y) dy, \text{ for all } (x, t) \in \mathbb{R}^n \times (0, T), \tag{1.9}$$

where $K_t(x, y) = K(x, t, y, 0)$ is the fundamental solution of \mathcal{H} , satisfying

$$\int_{\mathbb{R}^n} K_t(x, y) w(y) dy = 1, \text{ for all } (x, t) \in \mathbb{R}^n \times (0, T). \tag{1.10}$$

Furthermore, there exist $c, 1 \leq c < \infty$, and $\nu > 0$, both depending only on the structural constants, such that

$$K_t(x, y) \leq \frac{c}{\sqrt{w_t(x)w_t(y)}} e^{-\frac{|x-y|^2}{ct}}, \tag{1.11}$$

for all $t > 0, x, y \in \mathbb{R}^n$, and

$$\begin{aligned} |K_t(x+h, y) - K_t(x, y)| &\leq \frac{c}{\sqrt{w_t(x)w_t(y)}} \left(\frac{|h|}{t^{1/2} + |x-y|} \right)^\nu e^{-\frac{|x-y|^2}{ct}}, \\ |K_t(x, y+h) - K_t(x, y)| &\leq \frac{c}{\sqrt{w_t(x)w_t(y)}} \left(\frac{|h|}{t^{1/2} + |x-y|} \right)^\nu e^{-\frac{|x-y|^2}{ct}}, \end{aligned} \tag{1.12}$$

for all $t > 0, x, y, h \in \mathbb{R}^n$, satisfying $2|h| \leq t^{1/2} + |x-y|$.

Remark 1.3 The constant $\frac{1}{\sqrt{w_t(x)w_t(y)}}$ in Theorem 1.2 can be changed into one of

$$\frac{1}{w_t(x)}, \quad \frac{1}{w_t(y)}, \quad \frac{1}{\max(w_t(x), w_t(y))},$$

if the constant c is replaced with \tilde{c} which also depends on the structural constants, see [7, Rem. 3].

As discussed, in the non-degenerate case $w \equiv 1$, Theorem 1.2 is well known, and we refer to [1, 12] for the existence of the fundamental solution. After the groundbreaking work of Nash in [18], in which certain estimates of the fundamental solutions and Hölder continuity of the weak solutions were established, there were several important contributions in the field. As mentioned in [1], two-sided Gaussian bounds for the fundamental solutions were proved by employing by now the standard parabolic Harnack inequality. Subsequently, in [11] it was shown that Nash’s method can also be used to prove Aronson’s Gaussian bounds.

The quantitative estimates stated in Theorem 1.2 were proved in [6, 7] assuming in addition that A is symmetric and independent of t . We note that there are certain differences between [1, 2] and the approach used in [6, 7]. Indeed, in contrast to [1, 2, 6, 7] employ an argument along the lines of Davies [9] to derive Gaussian bounds. The latter argument relies on off-diagonal estimates, the Harnack inequality, and an $L^\infty(\mathbb{R}^n) \rightarrow L^2_w(\mathbb{R}^n)$ bound for the solution operator. Also, for the existence part, in [6, 7] the fact that $\mathcal{L} = -w^{-1} \operatorname{div}_x(A(x)\nabla_x)$ is induced through the accretive sesquilinear form,

$$\int_{\mathbb{R}^n} A(x)\nabla_x u \cdot \overline{\nabla_x v} dx,$$

is used. As a consequence, the exponential operator $e^{-t\mathcal{L}}$ is well-defined and the action of $e^{-t\mathcal{L}}$ on $L_w^2(\mathbb{R}^n)$ induces the fundamental solution. However, this idea does not work if A is time-dependent.

The contribution of this note is that we generalize the result of Cruz-Uribe and Rios in [6, 7, Thm. 1.3] to operators with (not necessarily symmetric) time-dependent coefficients. To accomplish this, we have to proceed differently compared to [6, 7], avoiding the use of the exponential operator $e^{-t\mathcal{L}}$, and we do so by first returning to the outstanding work of Kato [15]. In [15, Thm. I], existence and uniqueness of solutions to the initial value problem for the evolution equation

$$\frac{du}{dt} + \mathcal{A}(t)u = f(t), \quad 0 < t < T, \tag{1.13}$$

were studied. Here, the unknown $u = u(t)$ and the inhomogeneous term $f(t)$ are functions from the interval $[0, T]$ to a Banach space \mathcal{X} , whereas $\mathcal{A}(t)$ is a function from $[0, T]$ to the set of (in general unbounded) linear operators acting in \mathcal{X} . Given initial data in \mathcal{X} , in [15] the existence and uniqueness of solutions to the abstract Cauchy problem in Eq. 1.13 are proved assuming, roughly speaking, that (i) $-\mathcal{A}(t)$ is the infinitesimal generator of an analytic semigroup of operators; (ii) for some $h = 1/m$, where m is a positive integer, the domain of $(\mathcal{A}(t))^h$ is independent of t ; (iii) $\mathcal{A}(t)$ varies smoothly with t , see [15] and our discussion below.

In particular, to use [15, Thm. I, Thm. III] and to prove Theorem 1.2, we first note that in our case, $\mathcal{A}(t)$ is formally induced through

$$\langle \mathcal{A}(t)u, v \rangle := \langle \mathcal{L}u, v \rangle = \int_{\mathbb{R}^n} A(x, t) \nabla_x u \cdot \overline{\nabla_x v} \, dx.$$

While $\mathcal{A}(t)$ initially is an unbounded operator on $L_w^2(\mathbb{R}^n)$, we consider its restriction to

$$D(\mathcal{A}(t)) := \{u \in H_w^1(\mathbb{R}^n) : \mathcal{A}(t)u \in L_w^2(\mathbb{R}^n)\}. \tag{1.14}$$

Assuming sufficient regularity in t , (i) above follows from ellipticity. Furthermore, (ii) with $m = 2$ is a consequence of the solution of the Kato problem for degenerate elliptic operators, see [8]. However, if we have sufficient regularity in t , then (ii) also follows from [15] for some $m \geq 3$ and in this sense the solution of the Kato problem is not needed. Independent of method to conclude (ii), we prove, after an initial regularization of A in the time component and following [15], the existence of a kernel/fundamental solution to certain operators approximating our original operator. We then prove appropriate off-diagonal estimates by following the argument in [9, Lem.1], and we proceed as in [6, 7] to establish upper Gaussian bounds. Finally, we remove the regularization parameters and pass them to the limit in a convergence argument.

After some preliminaries, the rest of the paper is devoted to the proof of Theorem 1.2.

2 Preliminaries and Basic Assumptions

For general background and the results concerning weights cited here, we refer to [19, Ch. V]. The weight $w = w(x)$ is a real-valued function belonging to the Muckenhoupt class $A_2(\mathbb{R}^n, dx)$, that is,

$$[w]_{A_2} := \sup_Q \left(\int_Q w \, dx \right) \left(\int_Q w^{-1} \, dx \right) < \infty, \tag{2.1}$$

where the supremum is taken with respect to all cubes $Q \subset \mathbb{R}^n$. We introduce the measure $dw(x) := w(x) dx$ on \mathbb{R}^n , and we write $w(E) := \int_E dw$ for all Lebesgue measurable sets $E \subset \mathbb{R}^n$. It follows from Eq. 2.1 that there are constants $\eta \in (0, 1)$ and $\beta > 0$, depending only on n and $[w]_{A_2}$, such that

$$\beta^{-1} \left(\frac{|E|}{|Q|} \right)^{\frac{1}{2\eta}} \leq \frac{w(E)}{w(Q)} \leq \beta \left(\frac{|E|}{|Q|} \right)^{2\eta}, \tag{2.2}$$

whenever $E \subset Q$ is measurable and where $|\cdot|$ denotes Lebesgue measure in \mathbb{R}^n . In particular, there exists a constant D only depending on $[w]_{A_2}$ and n , called the doubling constant for w , such that

$$w(2Q) \leq Dw(Q) \text{ for all cubes } Q \subset \mathbb{R}^n. \tag{2.3}$$

Since, by equation Eq. 2.1, the function $\frac{1}{w}$ belongs to $A_2(\mathbb{R}^n, dx)$, Eq. 2.3 holds for $\frac{1}{w}$. For every $p \geq 1$ and $K \subset \mathbb{R}^n$, the space $L^p_w(K)$ is the space of all measurable functions $f : \mathbb{R}^n \rightarrow \mathbb{C}$ such that

$$\|f\|_{L^p_w(K)} := \left(\int_K |f|^p dw \right)^{\frac{1}{p}} < \infty.$$

We denote $L^p_w := L^p_w(\mathbb{R}^n)$.

We define $\langle \cdot, \cdot \rangle_w$ as the inner product induced by the norm $\| \cdot \|_{L^2_w}$. Using the A_2 -condition, we have

$$L^2_w \subset L^1_{loc}(\mathbb{R}^n, dx), \tag{2.4}$$

and the class $C^\infty_0(\mathbb{R}^n)$ of smooth and compactly supported test functions is dense in L^2_w via the usual truncation and the convolution procedure [16, Sec. 1]. Finally, we write $H^1_w := H^1_w(\mathbb{R}^n)$ for the space of all $f \in L^2_w$ for which the distributional gradient $\nabla_x f$ is (componentwise) in L^2_w , and we equip the space with the norm

$$\| \cdot \|_{H^1_w} := (\| \cdot \|_{2,w}^2 + (\| \nabla_x \cdot \|_{2,w}^2)^{1/2}.$$

By construction H^1_w is a Hilbert space and the standard truncation and convolution techniques yield that $C^\infty_0(\mathbb{R}^n)$ is dense in H^1_w , see [16, Thm. 2.5]. We also introduce the space $H^{1,1}_{w,0}(\mathbb{R}^n \times (0, T))$ as the completion of $C^\infty_0(\mathbb{R}^n \times (0, T))$ with the norm

$$(\| \cdot \|_{2,w}^2 + \|\partial_t \cdot\|_{2,w}^2 + \|\nabla_x \cdot\|_{2,w}^2)^{1/2}.$$

Given an operator \mathcal{L} defined on a subset of L^2_w , we introduce

$$D(\mathcal{L}) := \{u \in L^2_w : \mathcal{L}(u) \in L^2_w\}.$$

A quadratic form $\Phi : H^1_w \rightarrow \mathbb{R}$ is said to be closed if for every sequence $u_n \in H^1_w$, satisfying

$$\lim_{m,n \rightarrow \infty} \Phi[u_m - u_n] = 0 \text{ and } \lim_{i \rightarrow \infty} \|u_n - u\|_{L^2_w} = 0,$$

for some $u \in L^2_w$, we have $u \in H^1_w$ and that

$$\lim_{n \rightarrow \infty} \Phi[u_n - u] = 0.$$

From now on, the notation $A \lesssim B$ means that $A \leq cB$ for some constant c , depending at most on the structural constants unless otherwise stated. The notations $A \gtrsim B$ and $A \sim B$ should be interpreted similarly.

3 Proof of Theorem 1.2: Uniqueness

We here prove the uniqueness part of Theorem 1.2 by proceeding along the lines of the corresponding proof in [2, Lem. 1]. To prove uniqueness, it is enough to prove that if u is a weak solution to the problem in Eq. 1.3 such that

$$u \in L^\infty([0, T], L_w^2(\mathbb{R}^n)) \cap L^2((0, T], H_w^1(\mathbb{R}^n)),$$

and such that $u(\cdot, t) \rightarrow 0$ in $L_w^2(\mathbb{R}^n)$ as $t \rightarrow 0^+$, then $u = 0$ a.e. in $\mathbb{R}^n \times [0, T]$. We note that by an approximation in $C_0^\infty(\mathbb{R}^n \times (0, T))$, test functions in the space $H_{w,0}^{1,1}(\mathbb{R}^n \times (0, T))$ are allowed in the weak formulation of Eq. 1.3. To proceed, we fix $T' \in (0, T)$ such that $u(\cdot, T') \in L_w^2(\mathbb{R}^n)$, and we introduce

$$\zeta_h(t) := \begin{cases} t/h, & t \in [0, h], \\ 1, & t \in (h, T' - 2h], \\ (T' - h - t)/h, & t \in (T' - 2h, T' - h], \end{cases}$$

where $0 < h < T'/2$. Using ζ_h and the Steklov average of u , define

$$\phi_h(x, t) := \begin{cases} \zeta_h(t) \int_t^{t+h} u(x, s) \, ds, & (x, t) \in \mathbb{R}^n \times [0, T' - h], \\ 0, & (x, t) \in \mathbb{R}^n \times (T' - h, T]. \end{cases}$$

Then, $\phi_h \in H_{w,0}^{1,1}(\mathbb{R}^n \times (0, T))$. Furthermore, using ϕ_h as the test function in Eq. 1.3, and letting $h \rightarrow 0$, we deduce that

$$\int_{\mathbb{R}^n} u^2(x, 0) \, dw - \int_{\mathbb{R}^n} u^2(x, T') \, dw = \int_0^{T'} \int_{\mathbb{R}^n} A(x, t) \nabla_x u \cdot \nabla_x u \, dx \, dt \geq 0.$$

Hence,

$$\int_{\mathbb{R}^n} u^2(x, T') \, dw \leq \int_{\mathbb{R}^n} u^2(x, 0) \, dw = 0,$$

and $u(x, T') = 0$ for a.e. $x \in \mathbb{R}^n$. This completes the proof.

4 Proof of Theorem 1.2: Existence and Kernel Representation

We here prove the existence part of Theorem 1.2 and the stated representation in terms of a kernel. Our first step is to use [15, Thm. III], and to do so we in particular have to work with coefficients which are smooth in the time variable. Hence, we have to prove uniform estimates for a class of approximating operators and then pass to the limit. We divide the argument into a number of relevant steps.

4.1 Existence of Linear Evolution Operators Following Kato

Let $\rho \in C_0^\infty(-1, 1)$ be a non-negative function which integrates to 1. Given $l \in \mathbb{R}_+$ and $\rho_l(t) = l\rho(lt)$, we introduce $A_l(\cdot, t) = \rho_l * A(\cdot, t)$, i.e., we mollify the matrix-valued function A in the time variable only. Define the sesquilinear form

$$\Phi^l(t)(u, v) := \int_{\mathbb{R}^n} w^{-1} A_l(x, t) \nabla_x u \cdot \overline{\nabla_x v} \, dw + l^{-1} \int_{\mathbb{R}^n} u \overline{v} \, dw,$$

for every $u, v \in H_w^1$ and \mathcal{L}_l^t through

$$\langle \mathcal{L}_l^t u, v \rangle_w := \Phi^l(t)(u, v).$$

Formally,

$$\mathcal{L}_l^t = -w^{-1} \operatorname{div}_x(A_l(x, t)\nabla_x) + 1/l.$$

In \mathcal{L}_l^t and $\Phi^l(t)$, t should be seen as a parameter.

Let $\Phi^l(t)[u] := \Phi^l(t)(u, u)$ for every $u \in H_w^1$. Then,

$$\operatorname{Im} \Phi^l(t)[u] \leq \frac{c_2}{c_1} \operatorname{Re} \Phi^l(t)[u], \quad \operatorname{Re} \Phi^l(t)[u] \geq \min\{c_1, 1/l\} \|u\|_{H_w^1}^2, \tag{4.1}$$

for every $t \in \mathbb{R}, u \in H_w^1$. Let $u_n \in H_w^1$ be a sequence such that

$$\lim_{n \rightarrow \infty} \|u_n - u\|_{L_w^2} = 0,$$

for $u \in L_w^2$, and

$$\lim_{m, n \rightarrow \infty} \operatorname{Re} \Phi^l(t)[u_m - u_n] = 0.$$

Then, by Eq. 4.1, u_n is a Cauchy sequence in the Hilbert space H_w^1 . Hence,

$$\lim_{n \rightarrow \infty} \|u_n - u\|_{H_w^1} = 0,$$

and

$$\lim_{n \rightarrow \infty} \operatorname{Re} \Phi^l(t)[u_n] = \Phi^l(t)[u].$$

This proves that $\operatorname{Re} \Phi^l(t)$ is a closed quadratic form.

Now,

$$|\Phi^l(t)[u] - \Phi^l(s)[u]| = \left| \int_{\mathbb{R}^n} (A_l(x, t) - A_l(x, s)) \nabla_x u \cdot \overline{\nabla_x u} \, dx \right|$$

for all $s, t \in \mathbb{R}, u \in H_w^1$. Noting that

$$w^{-1}(x)(A_l(x, t) - A_l(x, s)) = \int w^{-1}(x)A(x, \tau)(\rho_l(\tau - t) - \rho_l(\tau - s)) \, d\tau,$$

we deduce that

$$|w^{-1}(x)(A_l(x, t) - A_l(x, s))| \lesssim \int |\rho_l(\tau - t) - \rho_l(\tau - s)| \, d\tau \lesssim l \|\partial_t \rho\|_{L^\infty} |t - s|,$$

for all $s, t \in \mathbb{R}$, where the second implicit constant also depends on ρ . Hence, by Eq. 4.1, we have

$$|\Phi^l(t)[u] - \Phi^l(s)[u]| \lesssim l \|\partial_t \rho\|_{L^\infty} |t - s| \|\nabla_x u\|_{L_w^2}^2 \lesssim l \|\partial_t \rho\|_{L^\infty} |t - s| \operatorname{Re} \Phi^l(s)[u],$$

for all $s, t \in \mathbb{R}, u \in H_w^1$. Now applying [15, Thm. III], we can conclude the following.

Theorem 4.1 *For every $T > 0$, there exists a unique bounded linear evolution operator $U_l(t, s) : L_w^2 \rightarrow L_w^2$, defined for $0 \leq s \leq t \leq T$, with the following properties:*

1. $U_l(t, s)$ is strongly continuous for $0 \leq s \leq t \leq T$ and

- (i) $U_l(t, t) = 1$, for all $t \geq 0$,
- (ii) $U_l(t, s)U_l(s, r) = U_l(t, r)$, for all $0 \leq r \leq s$.

2. For $0 \leq s < t$, the range of $U_I(t, s)$ is a subset of $D(\mathcal{L}_I^t)$, $\mathcal{L}_I^t U_I(t, s) : L_w^2 \rightarrow L_w^2$ is a bounded operator, $U_I(t, s)$ is strongly differentiable in t , and

$$(iii) \partial_t U_I(t, s) f + \mathcal{L}_I^t U_I(t, s) f = 0, \text{ for all } f \in L_w^2.$$

For simplicity, we will write \mathcal{L}_I instead of \mathcal{L}_I^t , hence suppressing the superscript t . We will need the following result.

Lemma 4.2 *If $f \in L_w^2$ is a real-valued non-negative function, then $U_I(t, 0) f$ is also real-valued and non-negative for all $t \geq 0$.*

Proof By property (i) of Theorem 4.1, the lemma is immediate for $t = 0$. Let $f \in L_w^2$ be a real-valued non-negative function and consider $t > 0$. Using the inequality

$$0 \leq \text{Re} \langle \mathcal{L}_I U_I(t, 0) f, U_I(t, 0) f - \text{Re } U_I(t, 0) f \rangle_w,$$

we have

$$\begin{aligned} 0 &\leq \text{Re} \langle \mathcal{L}_I U_I(t, 0) f, U_I(t, 0) f - \text{Re } U_I(t, 0) f \rangle_w \\ &= -\text{Re} \langle \partial_t U_I(t, 0) f, U_I(t, 0) f - \text{Re } U_I(t, 0) f \rangle_w \\ &= -\frac{1}{2} \partial_t \langle U_I(t, 0) f, U_I(t, 0) f \rangle_w + \frac{1}{2} \partial_t \langle \text{Re } U_I(t, 0) f, \text{Re } U_I(t, 0) f \rangle_w. \end{aligned}$$

Integrating from 0 to t in this inequality, we have

$$\langle U_I(t, 0) f, U_I(t, 0) f \rangle_w \leq \langle \text{Re } U_I(t, 0) f, \text{Re } U_I(t, 0) f \rangle_w.$$

In conclusion, $\text{Im } U_I(t, 0) f = 0$ and $U_I(t, 0) f$ is a real-valued function. Since both $\mathcal{L}_I U_I(t, 0) f$ and f belong to L_w^2 , we deduce that

$$\| \nabla_x U_I(t, 0) f \|_{L_w^2} \lesssim \langle \mathcal{L}_I U_I(t, 0) f, U_I(t, 0) f \rangle_w < \infty,$$

and that $\partial_t U_I(t, 0) f \in L_w^2$. By a standard argument, $\partial_t |U_I(t, 0) f|, \nabla_x |U_I(t, 0) f| \in L_w^2$ and

$$\left(\partial_t |U_I(t, 0) f|, \nabla_x |U_I(t, 0) f| \right) = \begin{cases} (\partial_t U_I(t, 0) f, \nabla_x U_I(t, 0) f) & \text{if } U_I(t, 0) f \geq 0, \\ (-\partial_t U_I(t, 0) f, -\nabla_x U_I(t, 0) f) & \text{if } U_I(t, 0) f < 0. \end{cases}$$

Using this, we deduce

$$\begin{aligned} 0 &\leq \text{Re} \langle \mathcal{L}_I U_I(t, 0) f, U_I(t, 0) f - |U_I(t, 0) f| \rangle_w \\ &= \text{Re} \langle -\partial_t U_I(t, 0) f, U_I(t, 0) f - |U_I(t, 0) f| \rangle_w \\ &= -\frac{1}{2} \langle \partial_t (U_I(t, 0) f - |U_I(t, 0) f|), U_I(t, 0) f - |U_I(t, 0) f| \rangle_w \\ &= -\frac{1}{4} \partial_t \langle U_I(t, 0) f - |U_I(t, 0) f|, U_I(t, 0) f - |U_I(t, 0) f| \rangle_w. \end{aligned}$$

Integrating from 0 to t in this inequality, we have $U_I(t, 0) f = |U_I(t, 0) f|$ and hence $U_I(t, 0) f$ is non-negative. □

4.2 An Off-diagonal Estimate and its Implications

Given two closed subsets $E, F \subset \mathbb{R}^n$, we let $\text{dist}(E, F)$ denote the Euclidean distance between the sets.

Lemma 4.3 *Let $E, F \subset \mathbb{R}^n$ be two closed subsets and let $d := \text{dist}(E, F)$. Then, there exists a constant $c > 0$, depending only on the structural constants, such that*

$$\|U_I(t, 0)(f1_E)\|_{L^2_w(F)} \lesssim e\left(-\frac{cd^2}{t}\right) \|f\|_{L^2_w(E)},$$

for every $t > 0$ and for all $f \in L^2_w(E)$.

Proof The argument is similar to [9, Lem. 1]. Let $\psi(x) := \text{dist}(x, F)$ and $\phi(x) := e^{\alpha\psi(x)}$, where α is a negative constant to be determined later. Then, by Young’s inequality for products, and the fact that $\|\nabla_x \psi\|_{L^\infty} \leq 1$, we have

$$\begin{aligned} \partial_t \|\phi U_I(t, 0)(f1_E)\|_{L^2_w}^2 &= -2\langle \mathcal{L}_I U_I(t, 0)(f1_E), \phi^2 U_I(t, 0)(f1_E) \rangle_w \\ &\leq -2\langle A_I \nabla_x (U_I(t, 0)(f1_E)), \nabla_x (\phi^2 U_I(t, 0)(f1_E)) \rangle_w \\ &\leq -2c_1 \|\phi \nabla_x (U_I(t, 0)(f1_E))\|_{L^2_w}^2 + \frac{2c_2}{\lambda} \|\phi \nabla_x (U_I(t, 0)(f1_E))\|_{L^2_w}^2 \\ &\quad + \lambda 2\alpha^2 c_2 \|\phi U_I(t, 0)(f1_E)\|_{L^2_w}^2, \end{aligned}$$

where $\lambda > 0$ is a degree of freedom. Letting $\lambda = c_2/c_1$, we obtain

$$\partial_t \|\phi U_I(t, 0)(f1_E)\|_{L^2_w}^2 \leq \frac{2\alpha^2 c_2^2}{c_1} \|\phi U_I(t, 0)(f1_E)\|_{L^2_w}^2.$$

Hence,

$$\|\phi U_I(t, 0)(f1_E)\|_{L^2_w}^2 \leq e\left(\frac{2\alpha^2 c_2^2 t}{c_1}\right) \|\phi f1_E\|_{L^2_w}^2.$$

In conclusion,

$$\begin{aligned} \int_F |U_I(t, 0)(f1_E)|^2 dw &\leq \int_{\mathbb{R}^n} |U_I(t, 0)(f1_E)|^2 \phi^2 dw \\ &\leq e\left(\frac{2\alpha^2 c_2^2 t}{c_1}\right) \|\phi f1_E\|_{L^2_w}^2 \\ &\lesssim e\left(\frac{2\alpha^2 c_2^2 t}{c_1} + 2\alpha d\right) \|f1_E\|_{L^2_w}^2. \end{aligned}$$

We conclude the proof by letting $\alpha = -(dc_1)/(2c_2^2 t)$. □

We introduce the cylinders

$$\begin{aligned} C_r(x_0, t_0) &:= \left\{ (x, t) : |t - t_0| < r^2, |x - x_0| < 2r \right\}, \\ C_r^+(x_0, t_0) &:= \left\{ (x, t) : 3r^2/4 < t - t_0 < r^2, |x - x_0| < r/2 \right\}, \\ C_r^-(x_0, t_0) &:= \left\{ (x, t) : -3r^2/4 < t - t_0 < -r^2/4, |x - x_0| < r/2 \right\}, \end{aligned}$$

for all $r > 0$ $(x_0, t_0) \in \mathbb{R}^n \times \mathbb{R}$. We refer to [5, Thm. 2.1], for autonomous coefficients, and [13, Thm. A] for the proof of the following Harnack inequality.

Lemma 4.4 *Let $(x_0, t_0) \in \mathbb{R}^n \times \mathbb{R}, r > 0$. If u is a non-negative weak solution of $\mathcal{H}u = 0$ in $Q_r(x_0, t_0)$, then*

$$\sup_{C_r^-(x_0, t_0)} u(x, t) \lesssim \inf_{C_r^+(x_0, t_0)} u(x, t).$$

To use the argument of Davies [9, Thm. 3] to prove the upper Gaussian bound, we prove the following estimate.

Lemma 4.5 *Let $\phi \in C_0^\infty(\mathbb{R}^n)$ and $\rho := \|\nabla_x \phi\|_{L^\infty}$. Then,*

$$\|\sqrt{w_t} e^{-\phi} U_l(t, r)(e^\phi f)\|_{L^\infty} \lesssim e^{\alpha(t-r)\rho^2} \|f\|_{L_w^2}, \quad 0 \leq r < t, \tag{4.2}$$

for all real-valued functions $f \in L_w^2$, where $\alpha > 0$ is a constant, depending on the structural constants.

Proof To prove the lemma, we proceed along the line of [6, 7, Sec. 5.1], using the previous lemmas. First, by the linearity of $U_l(t, 0)$, it is enough to consider the case that f is non-negative. Second, by homogeneity, it suffices to prove that

$$|e^{-\phi} U_l(1, 0)(e^\phi f)(0)| \lesssim e^{\alpha\rho^2} \|f\|_{L_w^2}. \tag{4.3}$$

Indeed, assume that Eq. 4.3 holds for every non-negative function $f \in L_w^2$, and consider the functions $u(x, t) := e^{-\phi} U_l(t, r)(e^\phi f)(x)$. Now, we consider $t, r > 0$ as fixed parameters and let

$$v^{t,r}(y, s) := u(x_0 + \sqrt{t-r}y, r + (t-r)s),$$

for $x_0 \in \mathbb{R}^n$ fixed and for all $y \in \mathbb{R}^n, s \in \mathbb{R}_+$. For $t, r > 0$ fixed, we have that $\partial_s v^{t,r}(y, s)$ equals

$$e^{-\phi} \left(-\frac{1}{w} \operatorname{div}_x A_l(\cdot, r + (t-r)s) \nabla_x + \frac{t-r}{l} \right) U(r + (t-r)s, r)(e^\phi f)(x_0 + \sqrt{t-r}y),$$

and $v^{t,r}(y, 0) = f(x_0 + \sqrt{t-r}y)$ for all $y \in \mathbb{R}^n$. Hence,

$$v^{t,r}(y, s) = e^{-\phi^{t,r}} U_l^{t,r}(s, 0) e^{\phi^{t,r}} f^{t,r}(y), \quad \text{for } y \in \mathbb{R}^n,$$

by the property of uniqueness, where

$$f^{t,r}(y) := f(x_0 + \sqrt{t-r}y), \quad \phi^{t,r}(y) := \phi(x_0 + \sqrt{t-r}y), \quad \text{for } y \in \mathbb{R}^n.$$

Furthermore, $U_l^{t,r}(s, 0)$ is as in Theorem 4.1 but induced by the operator

$$-(w^{t,r})^{-1} \operatorname{div}_x (A_l^{t,r} \nabla_x) + \frac{t-r}{l},$$

where

$$A_l^{t,r}(y, s) := A_l(x_0 + \sqrt{t-r}y, r + (t-r)s), \quad w^{t,r}(y) := w(x_0 + \sqrt{t-r}y), \quad \text{for } y \in \mathbb{R}^n.$$

Since $A_l^{t,r}$ satisfies

$$c_1 |\xi|^2 w^{t,r}(y) \leq A_l^{t,r}(y, s) \xi \cdot \xi, \quad |A_l^{t,r}(y, s) \xi \cdot \zeta| \leq c_2 w^{t,r}(y) |\xi| |\zeta|,$$

for all $y, \xi, \zeta \in \mathbb{R}^n, s \in \mathbb{R}_+$, $w^{t,r}$ is an A_2 -weight, and $[w^{t,r}]_2 = [w]_2$, the result stated in the lemma is now implied by applying Eq. 4.3 to the function $v^{t,r}$.

Finally, we prove Eq. 4.3. To start the argument, let $f \in L^2_w$ be a fixed non-negative function and let $Q_0 \subset \mathbb{R}^n$ be the cube centered at the origin with $\ell(Q_0) = 9$. We let $Q_k := 3^k Q_0$, and, for $k \geq 1$, $\{Q^{k,j}\}_{j=1}^{3^n-1}$ be a partition of $Q_k \setminus Q_{k-1}$ into cubes of side-length 3^{k+1} . Define $f^0 := f1_{Q_0}$ and $f^{k,j} := f1_{Q^{k,j}}$. Then,

$$|e^{-\phi} U_l(1, 0)(e^\phi f)(0)| \leq \sum_{k=1}^\infty \sum_{j=1}^{3^n-1} |e^{-\phi} U_l(1, 0)(e^\phi f^{k,j})(0)| + \sum_{j=1}^{3^n-1} |e^{-\phi} U_l(1, 0)(e^\phi f^0)(0)|. \tag{4.4}$$

Let $u^{k,j}(x, t) := U_l(t, 0)(e^\phi f^{k,j})(x)$ and $k \geq 1$. Then, by Lemma 4.2, $u^{k,j}$ is a non-negative weak solution of $\partial_t u + \mathcal{L}_l u = 0$. For $y \in \mathbb{R}^n, s \in \mathbb{R}_+$, define the function $v^{k,j}(y, s) := u^{k,j}(3^k y, s)$ which satisfies $\partial_t v^{k,j} + \tilde{\mathcal{L}}_l^k v^{k,j} = 0$ where

$$\tilde{\mathcal{L}}_l^k := -(w^k)^{-1} \operatorname{div}_x (A_l^k \nabla_x) + 1/l,$$

and $A_l^k(y, s) := A_l(3^k y, s), w^k(y) := w(3^k y)$. Then, by Lemma 4.4,

$$\sup_{Q_1^-(0, \frac{13}{8})} v^{k,j}(y, s) \lesssim \inf_{Q_1^+(0, \frac{13}{8})} v^{k,j}(y, s).$$

Hence,

$$v^{k,j}(0, 1) \lesssim \left(w^k(B_{\frac{1}{2}}(0)) \right)^{-\frac{1}{2}} \left(\int_{\frac{19}{8}}^{\frac{21}{8}} \int_{B_{\frac{1}{2}}(0)} |v^{k,j}(y, s)|^2 dw^k(y) ds \right)^{\frac{1}{2}}.$$

By change of variable, this implies that

$$u^{k,j}(0, 1) \lesssim \left(w_{\frac{3^k}{2}}(0) \right)^{-\frac{1}{2}} \left(\int_{\frac{19}{8}}^{\frac{21}{8}} \int_{B_{\frac{1}{2}}(0)} |v^{k,j}(y, s)|^2 dw^k(y) ds \right)^{\frac{1}{2}}.$$

Now, $e^\phi f^{k,j}$ is supported in $Q^{k,j}$ and $\operatorname{dist}(Q^{k,j}, B_{\frac{3^k}{2}}(0)) \geq \frac{3^k}{2}$. Hence, by Lemma 4.3,

$$\begin{aligned} & |u^{k,j}(0, 1)| \\ & \lesssim \left(w_{\frac{3^k}{2}}(0) \right)^{-\frac{1}{2}} e^{-c3^{2k}} \left(\int_{\frac{19}{8}}^{\frac{21}{8}} \int_{Q^{k,j}} e^{2(\phi(x)-\phi(0))} |f^{k,j}(y, s)|^2 dw^k(y) ds \right)^{\frac{1}{2}} \\ & \lesssim \left(w_{\frac{3^k}{2}}(0) \right)^{-\frac{1}{2}} e^{(-c3^{2k}+3^{k+1} \frac{\sqrt{n}}{2} \rho)} \|f^{k,j}\|_{L^2_w}. \end{aligned} \tag{4.5}$$

By Lemma 4.3 and a similar estimate as above, we obtain

$$e^{-\phi(0)} |U_l(1, 0)(e^{-\phi} f^0)(0)| \lesssim e^{(9 \frac{\sqrt{n}}{2} \rho)} \|f^0\|_{L^2_w}. \tag{4.6}$$

Now, by summing Eqs. 4.4, 4.5, and 4.6, we see that

$$\begin{aligned}
 & e^{-\phi(0)}|U_t(1, 0)(e^\phi f)(0)| \\
 & \lesssim \left(e^{9\sqrt{n}\rho} + \sum_{k=1}^\infty \sum_{j=1}^{3^n-1} \left(w_{\frac{3^k}{2}}(0) \right)^{-1} e^{(-2c3^{2k}+3^{k+1}\sqrt{n}\rho)} \right)^{\frac{1}{2}} \left(\|f^0\|_{L_w^2}^2 + \sum_{k=1}^\infty \sum_{j=1}^{3^n-1} \|f^{k,j}\|_{L_w^2}^2 \right)^{\frac{1}{2}} \\
 & \leq \left(e^{9c} e^{\frac{9n}{c}\rho^2} + 3^n e^{\frac{9n}{c}\rho^2} \sum_{k=1}^\infty \left(w_{\frac{3^k}{2}}(0) \right)^{-1} e^{(-c3^{2k})} \right)^{\frac{1}{2}} \|f\|_{L_w^2} \\
 & \lesssim e^{\alpha\rho^2} \|f\|_{L_w^2},
 \end{aligned}$$

where α depends on the structural constants. In the inequalities above, Cauchy-Schwarz inequality is used on the first inequality, and Eq. 2.3 is used on the last inequality. This completes the proof of Eq. 4.3. \square

4.3 Kernel Estimates for the Operator $U_t(t, 0)$

We here prove the Gaussian upper bound estimates for U_t .

Theorem 4.6 *There exists a kernel $K_t^1(x, y)$ associated with the operator $U_t(t, 0)$ such that*

$$U_t(t, 0)(f)(x) = \int_{\mathbb{R}^n} K_t^1(x, y) f(y) \, dw(y), \tag{4.7}$$

for all $f \in L_w^2(\mathbb{R}^n)$ and $x \in \mathbb{R}^n$. Furthermore, there exist a constant $c, 1 \leq c < \infty$, and $\nu > 0$, both depending only on the structural constants, such that

$$K_t^1(x, y) \lesssim \frac{c}{\sqrt{w_t(x)w_t(y)}} e^{-\frac{|x-y|^2}{ct}}, \tag{4.8}$$

for all $t > 0, x, y \in \mathbb{R}^n$, and such that

$$\begin{aligned}
 |K_t^1(x+h, y) - K_t^1(x, y)| & \lesssim \frac{1}{\sqrt{w_t(x)w_t(y)}} \left(\frac{|h|}{t^{1/2} + |x-y|} \right)^\nu e^{-\frac{|x-y|^2}{ct}}, \\
 |K_t^1(x, y+h) - K_t^1(x, y)| & \lesssim \frac{1}{\sqrt{w_t(x)w_t(y)}} \left(\frac{|h|}{t^{1/2} + |x-y|} \right)^\nu e^{-\frac{|x-y|^2}{ct}},
 \end{aligned} \tag{4.9}$$

for all $t > 0, x, y, h \in \mathbb{R}^n$, where $2|h| \leq t^{1/2} + |x-y|$.

Proof By Lemma 4.2 and a duality argument,

$$\|e^{-\phi} U_t(t, 0)(\sqrt{w_t} e^\phi f)\|_{L_w^2} \lesssim e^{\alpha t \rho^2} \|f\|_{L_w^1}, \tag{4.10}$$

for every $f \in L_w^1$ and $\phi \in C_0^\infty(\mathbb{R}^n)$, where $\rho = \|\nabla_x \phi\|_{L^\infty}$ and α is a positive constant depending on structural constants. By property (ii) in Theorem 4.1, we have

$$U_t(t, 0) = U_t(t, t/2)U_t(t/2, 0),$$

for all $t \in \mathbb{R}_+$. Hence, by combining Eqs. 4.2 and 4.10, we obtain

$$\|\sqrt{w_t} e^{-\phi} U_t(t, 0)(\sqrt{w_t} e^\phi f)\|_{L^\infty} \lesssim e^{\alpha t \rho^2} \|f\|_{L_w^1}, \tag{4.11}$$

for every $f \in L^1_w$. Therefore, by the Dunford-Pettis theorem [10, Thm. 1.3.2], there exists a kernel $K_t^{l,\phi}$ which satisfies

$$\sqrt{w_t}e^{-\phi}U_t(t, 0)(\sqrt{w_t}e^\phi f)(x) = \int_{\mathbb{R}^n} K_t^{l,\phi}(x, y)f(y) dw(y),$$

for all $f \in L^1_w, \phi \in C^\infty_0(\mathbb{R}^n), x \in \mathbb{R}^n$. Furthermore,

$$|K_t^{l,\phi}(x, y)| \lesssim e^{\alpha t \rho^2},$$

for all $t > 0, x, y \in \mathbb{R}^n$. Choosing $\phi = 0$, a kernel $K_t^l(x, y)$ is obtained such that

$$U_t(t, 0)(f)(x) = \int_{\mathbb{R}^n} K_t^l(x, y)f(y) dw(y),$$

for all $f \in L^1_w$. Note that $K_t^l(x, y) = \sqrt{w_t(x)w_t(y)}e^{\phi(x)-\phi(y)}K_t^{l,\phi}(x, y)$ and hence

$$|K_t^l(x, y)| \lesssim \frac{1}{\sqrt{w_t(x)w_t(y)}}e^{\alpha t \rho^2}e^{\phi(x)-\phi(y)}, \tag{4.12}$$

for every $\phi \in C^\infty_0(\mathbb{R}^n)$ such that $\|\nabla_x \phi\|_{L^\infty} = \rho$. By an approximation argument we can assume that ϕ is a Lipschitz function in Eq. 4.12. Taking infimum of $\phi(x) - \phi(y)$ on Eq. 4.12 over Lipschitz functions ϕ satisfying $\|\nabla_x \phi\|_{L^\infty} = \rho$, we obtain

$$|K_t^l(x, y)| \lesssim \frac{1}{\sqrt{w_t(x)w_t(y)}}e^{\alpha t \rho^2 - \rho|x-y|},$$

for all $\rho > 0$. Then, putting $\rho = \frac{|x-y|}{2\alpha t}$ concludes that

$$|K_t^l(x, y)| \lesssim \frac{1}{\sqrt{w_t(x)w_t(y)}}e^{-\frac{|x-y|^2}{4\alpha t}}, \tag{4.13}$$

for all $x, y \in \mathbb{R}^n, t > 0$. Finally, Eq. 4.13, Lemma 4.4, and an argument due to Trudinger, see the proof of [20, Thm. 2.2], imply the inequalities in Eq. 4.9. \square

4.4 Completing the Argument: Passing to the Limit

We need the following remark for the Hölder regularity of solutions.

Remark 4.7 Given $f \in L^2_w$, for every $l \in \mathbb{R}_+$ the solution $U_l(t, 0)f(x)$ is Hölder continuous on small closed disks $D \subset \mathbb{R}^n \times \mathbb{R}_+$, such that $2D \subset \mathbb{R}^n \times \mathbb{R}_+$, with bounds depending on the radius of D , the structural constants, and $\|U_l(t, 0)f\|_{L^\infty(2D)}$, see [13, Thm. B]. Note that in [13, Thm. B] an extra assumption on w is required, see property (A5) in [13, Thm. B], to obtain interior Hölder regularity. However, the author uses this assumption only to derive the estimates (3.11) and (3.12) in [13], which hold for the equation in Theorem 4.1(iii).

Now, we show that $K_t^l(x, y)$ is also Hölder continuous on compact subsets of $\mathbb{R}^n \times \mathbb{R}^n \times \mathbb{R}_+$.

Lemma 4.8 *For every $l \in \mathbb{R}_+$, the functions $K_t^l(x, y)$ is Hölder continuous on compact subsets of $\mathbb{R}^n \times \mathbb{R}^n \times \mathbb{R}_+$ with bounds independent of l .*

Proof Let fix $x \in \mathbb{R}^n, t, l \in \mathbb{R}_+$. Define the functions

$$f_{z,r}(\cdot) := \frac{1}{w(B_r(z))}1_{B_r(z)}(\cdot)$$

for every $0 < r < 1, z \in \mathbb{R}^n$. Then,

$$U_l(t, 0)f_{z,r}(x) = \int_{\mathbb{R}^n} K_l^l(x, y)f_{z,r}(y) \, dw(y)$$

by Theorem 4.6 and $U_l(t, 0)f_{z,r}(x)$ is Hölder continuous on small closed disks $D \subset \mathbb{R}^n \times \mathbb{R}_+$, such that $2D \subset \mathbb{R}^n \times \mathbb{R}_+$, see Remark 4.7, and the Hölder bounds depend on radius of D , the structural constants, and $\|U_l(t, 0)f_{z,r}\|_{L^\infty(2D)}$. Now, by letting $\phi \equiv 0$ in Eq. 4.11, we obtain

$$|U_l(t, 0)f_{z,r}(x)| \lesssim \frac{1}{\sqrt{w(B_{\sqrt{t}}(x))}} \|f_{z,r}/\sqrt{w_t}\|_{L_w^1} \leq \frac{1}{\sqrt{w(B_{\sqrt{t}}(x))w(B_{\sqrt{t}/2}(z))}},$$

for every $x \in \mathbb{R}^n, t > 4r^2$. Consequently,

$$\frac{1}{w(B_r(z))} \int_{B_r(z)} K_l^l(x, y) \, dw(y)$$

is Hölder continuous on compact subsets of $\mathbb{R}^n \times \mathbb{R}_+$ with bounds independent of l, r . Letting $r \rightarrow 0$ and using the Lebesgue differentiation theorem, we obtain, for every fixed $z \in \mathbb{R}^n$, that $K_l^l(x, z)$ is Hölder continuous on compact subsets of $\mathbb{R}^n \times \mathbb{R}_+$ with bounds independent of l . Using the triangle inequality, we have

$$\begin{aligned} |K_l^l(x, y) - K_{l+h}^l(x', y')| &\leq |K_l^l(x, y) - K_l^l(x, y')| + |K_l^l(x, y') - K_l^l(x', y')| \\ &\quad + |K_l^l(x', y') - K_{l+h}^l(x', y')|, \end{aligned}$$

for every $x, y, x', y' \in \mathbb{R}^n, t, h, l \in \mathbb{R}_+$.

Hence, using this we conclude the lemma by Theorem 4.6 and the previous result that $K_l^l(x, z)$ is Hölder continuous on compact subsets of $\mathbb{R}^n \times \mathbb{R}_+$, for every fixed $z \in \mathbb{R}^n$, with bounds independent of l . □

To complete the proof of Theorem 1.2, we pass to the limit $l \rightarrow \infty$ in Theorem 4.6. To start the argument, we first note that

$$\partial_t \|U_l(t, 0)f\|_{L_w^2}^2 = -2\langle \mathcal{L}_l U_l(t, 0)f, U_l(t, 0)f \rangle_w \leq -2c_1 \|\nabla_x U_l(t, 0)f\|_{L_w^2}^2.$$

Hence,

$$\begin{aligned} \|U_l(t, 0)f\|_{L_w^2}^2 &\leq \|f\|_{L_w^2}^2, \\ \int_0^t \int_{\mathbb{R}^n} |\nabla_x U_l(s, 0)f|^2 \, dw \, ds &\leq \frac{1}{2c_1} \|f\|_{L_w^2}^2, \end{aligned} \tag{4.14}$$

and

$$\int_0^t \int_{\mathbb{R}^n} |U_l(s, 0)f|^2 \, dw \, ds \leq T \|f\|_{L_w^2}^2, \tag{4.15}$$

for all $t \in [0, T]$. In conclusion, up to a subsequence $U_l(t, 0)f(x)$ converges weakly to an element in $L^2([0, T], L_w^2)$ as $l \rightarrow \infty$. We denote the limit $U(t, 0)f(x)$. Moreover, we have that $\{\nabla_x U_l(t, 0)f\}$ converges weakly to $\nabla_x U(t, 0)f$ in $L^2([0, T], L_w^2(\mathbb{R}^n, \mathbb{R}^n))$. As a consequence of this, Eqs. 4.14, 4.15, we obtain

$$U(t, 0)f \in L^\infty([0, T], L_w^2(\mathbb{R}^n)) \cap L^2((0, T], H_w^1(\mathbb{R}^n)), \tag{4.16}$$

and

$$\begin{aligned} \sup_{t \in [0, T]} \|U(t, 0)f\|_{L^2_w}^2 + \int_0^T \int_{\mathbb{R}^n} |\nabla_x U(s, 0)f|^2 \, dw \, ds &\lesssim \|f\|_{L^2_w}^2, \\ \int_0^T \int_{\mathbb{R}^n} |U(s, 0)f|^2 \, dw \, ds &\leq T \|f\|_{L^2_w}^2. \end{aligned} \tag{4.17}$$

Furthermore, $u(x, t) := U(t, 0)f(x)$ is a weak solution to

$$\partial_t u + \mathcal{L}u = 0 \text{ in } \mathbb{R}^n \times (0, T). \tag{4.18}$$

Recall that

$$U_t(t, 0)f(x) = \int_{\mathbb{R}^n} K_t^l(x, y)f(y) \, dw(y) \text{ for all } (x, t) \in \mathbb{R}^n \times [0, T].$$

Using this, the uniform boundedness and the Hölder continuity of $K_t^l(x, y)$ on compact subsets of $\mathbb{R}^n \times \mathbb{R}^n \times \mathbb{R}_+$ with bounds independent of l , see Theorem 4.6 and Lemma 4.8, and the Arzelà-Ascoli theorem, we conclude that there exists a $K_t(x, y)$ such that $K_t^l(x, y)$ converges, up to a subsequence, uniformly to $K_t(x, y)$ on compact subsets of $\mathbb{R}^n \times \mathbb{R}^n \times \mathbb{R}_+$. Also,

$$\int_{\mathbb{R}^n} K_t(x, y)w(y) \, dy = 1, \text{ for all } (x, t) \in \mathbb{R}^n \times (0, T). \tag{4.19}$$

To prove this, note that

$$\begin{aligned} &\int_{\mathbb{R}^n} \frac{1}{\sqrt{w_t(x)w_t(y)}} e^{-\frac{|x-y|^2}{4\alpha t}} \, dw(y) \\ &\leq \frac{1}{\sqrt{w_t(x)}} \left(\int_{B_t(x)} \frac{1}{\sqrt{w_t(y)}} \, dw(y) + \sum_{k=1}^{\infty} e^{-\frac{2^2(k-1)t}{4\alpha}} \int_{B_{2^k t}(x) \setminus B_{2^{k-1} t}(x)} \frac{1}{\sqrt{w_t(y)}} \, dw(y) \right) \\ &\lesssim c(x, t), \end{aligned}$$

using Eqs. 2.2 and 2.3, where $c(x, t)$ is a constant which depends on x and t . In conclusion, Eq. 4.19 is a result of pointwise convergence of $K_t^l(x, y)$ to $K(x, y)$ as $l \rightarrow \infty$, Theorem 4.6, and Lebesgue’s dominated convergence theorem. Hence, by Theorem 4.6, there exists c , $1 \leq c < \infty$, and $\nu > 0$, both depending only on the structural constants, such that

$$K_t(x, y) \leq \frac{c}{\sqrt{w_t(x)w_t(y)}} e^{-\frac{|x-y|^2}{ct}}, \tag{4.20}$$

for all $t > 0$, $x, y \in \mathbb{R}^n$, and such that

$$\begin{aligned} |K_t(x+h, y) - K_t(x, y)| &\leq \frac{c}{\sqrt{w_t(x)w_t(y)}} \left(\frac{|h|}{t^{1/2} + |x-y|} \right)^\nu e^{-\frac{|x-y|^2}{ct}}, \\ |K_t(x, y+h) - K_t(x, y)| &\leq \frac{c}{\sqrt{w_t(x)w_t(y)}} \left(\frac{|h|}{t^{1/2} + |x-y|} \right)^\nu e^{-\frac{|x-y|^2}{ct}}, \end{aligned} \tag{4.21}$$

for all $t > 0$, $x, y, h \in \mathbb{R}^n$, satisfying $2|h| \leq t^{1/2} + |x-y|$.

We next prove that

$$U(t, 0)f(x) = \int_{\mathbb{R}^n} K_t(x, y)f(y) \, dw(y) \text{ for all } (x, t) \in \mathbb{R}^n \times (0, T). \tag{4.22}$$

To do this we first note, using Theorem 4.6 and Remark 1.3,

$$K_t^l(x, y) \lesssim \frac{1}{\sqrt{w_t(x)}} e^{-\frac{|x-y|^2}{ct}}, \tag{4.23}$$

for all $x, y \in \mathbb{R}^n, t \in \mathbb{R}_+$, and

$$\left| \int_{\mathbb{R}^n} \frac{e^{-\frac{|x-y|^2}{ct}}}{w_t(x)} |f(y)| dw(y) \right|^2 \leq \frac{1}{w_t^2(x)} \left(\int_{\mathbb{R}^n} |f(y)|^2 dw(y) \right) \left(\int_{\mathbb{R}^n} \frac{e^{-\frac{2|x-y|^2}{ct}}}{w(y)} dy \right),$$

for all $(x, t) \in \mathbb{R}^n \times \mathbb{R}_+$. Using Eq. 2.3, we have

$$\begin{aligned} \frac{1}{w_t^2(x)} \int_{\mathbb{R}^n} \frac{e^{-\frac{2|x-y|^2}{ct}}}{w(y)} dy &\leq \frac{1}{w_t^2(x)} \left(\int_{B_1(x)} \frac{1}{w(y)} dy + \sum_{k=1}^{\infty} e^{-\frac{2(2k-1)}{ct}} \int_{B_{2^k(x)} \setminus B_{2^{k-1}}(x)} \frac{1}{w(y)} dy \right) \\ &\lesssim c(x, t), \end{aligned}$$

where $c(x, t)$ is a constant which depends on x and t , and hence

$$\left| \int_{\mathbb{R}^n} \frac{e^{-\frac{|x-y|^2}{ct}}}{w_t(x)} |f(y)| dw(y) \right|^2 \lesssim c(x, t) \left(\int_{\mathbb{R}^n} |f(y)|^2 dw(y) \right). \tag{4.24}$$

In conclusion, by pointwise convergence of $K_t^l(x, y)$ to $K_t(x, y)$ as $l \rightarrow \infty$ and Lebesgue’s dominated convergence theorem, we obtain

$$\lim_{l \rightarrow \infty} U_l(t, 0) f(x) = \int_{\mathbb{R}^n} K_t(x, y) f(y) dw(y), \tag{4.25}$$

for all $x \in \mathbb{R}^n$. Let $\phi \in C_0^\infty(\mathbb{R}^n \times (0, T))$, let $K \subset \mathbb{R}^n$ be a compact set, and let $\epsilon > 0$ be such that the support of ϕ is contained in $K \times (\epsilon, T)$. Using Eq. 2.2 and Lemma 4.5, we have

$$|U_l(t, 0) f(x)| \lesssim \frac{\|f\|_{L_w^2}}{\sqrt{w_t(x)}},$$

for all $(x, t) \in \mathbb{R}^n \times \mathbb{R}_+$, and

$$\int_0^T \int_{\mathbb{R}^n} \frac{\|f\|_{L_w^2} |\phi(x, t)|}{\sqrt{w_t(x)}} dw(x) dt \lesssim T \tilde{c}(K, \epsilon) \|\phi\|_{L^\infty} \|f\|_{L_w^2},$$

where $\tilde{c}(K, \epsilon)$ is a constant which depends on K and ϵ . Thus, by Eq. 4.25 and Lebesgue’s dominated convergence theorem, we obtain

$$\begin{aligned} &\lim_{l \rightarrow \infty} \int_0^T \int_{\mathbb{R}^n} (U_l(t, 0) f(x)) \phi(x, t) dw(x) dt \\ &= \int_0^T \iint_{\mathbb{R}^n \times \mathbb{R}^n} K_t(x, y) f(y) \phi(x, t) dw(y) dw(x) dt \end{aligned} \tag{4.26}$$

whenever $f \in L_w^2$. As $U_l(t, 0) f(x)$ converges weakly to $U(t, 0) f(x)$ in $L^2([0, T], L_w^2)$, we have that

$$\int_0^T \int_{\mathbb{R}^n} (U_l(t, 0) f(x)) \phi(x, t) dw(x) dt \rightarrow \int_0^T \int_{\mathbb{R}^n} (U(t, 0) f(x)) \phi(x, t) dw(x) dt, \tag{4.27}$$

as $l \rightarrow \infty$ and whenever $\phi \in C_0^\infty(\mathbb{R}^n \times (0, T))$. Then, Eqs. 4.27 and 4.26 imply Eq. 4.22.

Finally, we have to prove that $U(t, 0)f(\cdot) \rightarrow f(\cdot)$ in $L^2_w(\mathbb{R}^n)$ as $t \rightarrow 0^+$. Assume first that $f \in C_0^\infty(\mathbb{R}^n)$ with support on a ball $B \subset \mathbb{R}^n$. For every $c > 0$, denote cB as the ball keeping the center of B and dilating its radius by c . Then, by Cauchy-Schwarz inequality, Eq. 4.19, and Lemma 4.3,

$$\begin{aligned} \|U(t, 0)f - f\|_{L^2_w}^2 &\leq \int_{2B} \left| \int_{\mathbb{R}^n} K_t(x, y) |(f(y) - f(x))| \, dw(y) \right|^2 dw(x) \\ &\quad + \sum_{k=1}^\infty \int_{2^{k+2}B \setminus 2^{k+1}B} |U(t, 0)f(x)|^2 dw(x) \\ &\leq \int_{2B} \left(\int_{\mathbb{R}^n} K_t(x, y) |f(y) - f(x)|^2 dw(y) \right) \left(\int_{\mathbb{R}^n} K_t(x, y) dw(y) \right) dw(x) \\ &\quad + \sum_{k=1}^\infty e^{-\frac{2^k}{ct}} \int_B |f(x)|^2 dw(x) \\ &\lesssim \int_{2B} \int_{\mathbb{R}^n} K_t(x, y) |f(y) - f(x)|^2 dw(y) dw(x) + t \|f\|_{L^2_w}^2, \end{aligned}$$

for $t \in \mathbb{R}_+$. As the second term on the right-hand side goes to zero as $t \rightarrow 0$, it is enough to control the first term. Now, for $t, \delta \in \mathbb{R}_+$ small enough, we have

$$\begin{aligned} &\int_{2B} \int_{\mathbb{R}^n} K_t(x, y) |f(y) - f(x)|^2 dw(y) dw(x) \\ &\leq \delta^2 w(2B) \|\nabla f\|_{L^\infty}^2 + \int_{2B} \int_{\mathbb{R}^n \setminus B_\delta(x)} K_t(x, y) |f(y) - f(x)|^2 dw(y) dw(x) \end{aligned}$$

and, by Eqs. 2.2, 2.3, 4.23, and pointwise convergence of $K_t^l(x, y)$ to $K_t(x, y)$ as $l \rightarrow \infty$, we arrive at

$$\begin{aligned} &\int_{2B} \int_{\mathbb{R}^n \setminus B_\delta(x)} K_t(x, y) |f(y) - f(x)|^2 dw(y) dw(x) \\ &\lesssim \|f\|_{L^\infty}^2 \int_{2B} \frac{1}{w_t(x)} \int_{\mathbb{R}^n \setminus B_\delta(x)} e^{-\frac{|y-x|^2}{ct}} dw(y) dw(x) \\ &= \|f\|_{L^\infty}^2 \int_{2B} \frac{1}{w_t(x)} \sum_{k=1}^\infty \int_{B_{2^k\delta}(x) \setminus B_{2^{k-1}\delta}(x)} e^{-\frac{|y-x|^2}{ct}} dw(y) dw(x) \\ &\lesssim \|f\|_{L^\infty}^2 \int_{2B} \frac{1}{w_t(x)} \sum_{k=1}^\infty e^{-\frac{2^{2(k-1)}\delta^2}{ct}} w(B_{2^k\delta}(x)) dw(x) \\ &\lesssim \|f\|_{L^\infty}^2 \int_{2B} \frac{1}{w_t(x)} \sum_{k=1}^\infty e^{-\frac{2^{2(k-1)}\delta^2}{ct}} D^k w(B_\delta(x)) dw(x) \\ &\lesssim \|f\|_{L^\infty}^2 |B| \frac{t^{m-\frac{n}{\eta}}}{\delta^{2m-\frac{n}{\eta}}}, \end{aligned}$$

where m is the smallest integer, such that $m > \frac{n}{\eta}$. Hence, letting first $t \rightarrow 0$, we obtain

$$\limsup_{t \rightarrow 0} \|U(t, 0)f - f\|_{L^2_w}^2 \lesssim \delta^2 w(2B) \|\nabla f\|_{L^\infty}^2.$$

Since δ can be arbitrarily small, we deduce $\lim_{t \rightarrow 0} \|U(t, 0)f - f\|_{L^2_w}^2 = 0$. We next use the fact that $C_0^\infty(\mathbb{R}^n)$ is dense in $L^2_w(\mathbb{R}^n)$. Indeed, consider $f \in L^2_w(\mathbb{R}^n)$ and let $f_j \in C_0^\infty(\mathbb{R}^n)$ be

such that $f_j \rightarrow f$ in $L^2_w(\mathbb{R}^n)$ as $j \rightarrow \infty$. We construct a solution $u_j(x, t) := U(t, 0)f_j(x)$ as above for every j . Then, by Eq. 4.17 and the linearity and uniqueness part of Theorem 1.2, we have

$$\begin{aligned} \sup_{t \in [0, T]} \|u - u_j\|_{L^2_w}^2 + \int_0^T \int_{\mathbb{R}^n} |\nabla_x(u - u_j)|^2 \, dw \, ds &\lesssim \|f - f_j\|_{L^2_w}^2 \rightarrow 0, \\ \int_0^T \int_{\mathbb{R}^n} |u - u_j|^2 \, dw \, ds &\lesssim T \|f - f_j\|_{L^2_w}^2 \rightarrow 0, \end{aligned}$$

as $j \rightarrow \infty$. Hence,

$$\begin{aligned} \|u(\cdot, t) - f(\cdot)\|_{L^2_w}^2 &\lesssim \|u(\cdot, t) - u_j(\cdot, t)\|_{L^2_w}^2 + \|u_j(\cdot, t) - f_j(\cdot)\|_{L^2_w}^2 + \|f_j(\cdot) - f(\cdot)\|_{L^2_w}^2 \\ &\lesssim \|u_j(\cdot, t) - f_j(\cdot)\|_{L^2_w}^2 + \|f_j(\cdot) - f(\cdot)\|_{L^2_w}^2. \end{aligned}$$

Let $\epsilon' > 0$ be small, and choose j large enough so that

$$\|f_j(\cdot) - f(\cdot)\|_{L^2_w}^2 < \epsilon'/2.$$

With j fixed, we choose $\delta' > 0$ small enough so that

$$\|u_j(\cdot, t) - f_j(\cdot)\|_{L^2_w}^2 < \epsilon'/2 \text{ for all } t \in [0, \delta').$$

We can then conclude, for $\epsilon' > 0$ given, that

$$\|u(\cdot, t) - f(\cdot)\|_{L^2_w}^2 \lesssim \epsilon \text{ for all } t \in [0, \delta').$$

This proves that $U(t, 0)f \rightarrow f$ in $L^2_w(\mathbb{R}^n)$ as $t \rightarrow 0^+$, whenever $f \in L^2_w(\mathbb{R}^n)$. The proof of Theorem 4.6 is therefore complete.

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